

Agenda

- Last time (Sept-14 7:30pm-8:45 / Sept-15 3:00-4:15pm)
 - Processes/Threads (chpt 4 + 5)
- This time (Tues Sept 19)
 - Threads (chpt 5)
 - CPU scheduling (chpt 6)
- Next time (Thurs Sept 21)
 - CPU sched (chpt 6)
 - Intro Synchronization (chpt 7)
- Extra class meeting this week (Thurs/Friday)!
- PA#2 due Thurs Sept 21 11am

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Before we start

- Windows executive can sometimes service the request without going to the particular subsystem (e.g., Windows "ReadFile()")
- TA office hours (all in 002a):
 - Wittawat: Wed 6-8pm
 - Dhruv: Thurs 7-9pm
 - Ray: Mon 5-7pm 002a

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Before we start: PA#2

- An critical skill: PATTERN MATCHING!
- What should happen when I execute "unhide" twice in a row?
- NOTE: try "ebp-8" as necessary
- "GetProcAddress" of NtGetCurrentProcessorNumber in ntdll.dll ??? What's up with that???
- Part-2: Q2: step 2.2.6: the output could be "nothing".

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From last time: More Complicated

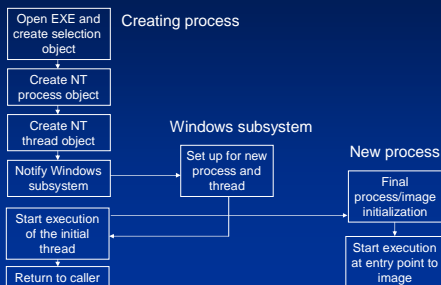
```
int main() {
    char prgname[1024];
    pid_t pid;
    int status;

    if (!fgets(prgname, 1024, stdin) == NULL) {
        printf("Did not read program name. Aborting!\n");
        exit(1);
    }
    prgname[strlen(prgname)-1]=0;

    if ((pid = fork()) == -1) {
        perror("fork");
        exit(1);
    }
    if (pid == 0) {
        execlp(prgname, prgname, 0);
        printf("%d I did not find program '%s'\n", getpid(), prgname);
        exit(1);
    } else {
        waitpid(pid, &status, 0);
        if (status == 0) printf("Program '%s' finished!\n", prgname);
    }
    return 0;
}
```

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The main Stages Windows follows to create a process



Context Switch

- To run a process, the OS loads the values of the hardware registers (PC, SP, other registers) from the values stored in that process' PCB
- As the program executes, the CPU registers changes values (PC, SP)
- When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process
- Context-switching is overhead; the system does no useful work while switching
- The duration of a context switch is dependent on hardware
- Typically, time sharing OS performs 100 to 1000 context switches per second
- Picture on next slide....

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Context Switch

The diagram illustrates the context switch process between two processes, P_0 and P_1 , managed by the operating system. The process is shown as a vertical timeline for each process, with the OS acting as the central controller.


- Initial State:** Process P_0 is in the "executing" state (indicated by a downward arrow).
- Interrupt or System Call:** An event triggers the OS to perform a context switch.
- Save State:** The OS saves the state of P_0 into its PCB₀ (represented by a box labeled "save state into PCB₀").
- Reload State:** The OS reloads the state of P_1 from its PCB₁ (represented by a box labeled "reload state from PCB₁").
- Idle Period:** The OS is in an "idle" state (indicated by a bracket labeled "idle") while the state is being saved and reloaded.
- Execution Resumes:** Process P_1 begins "executing" (indicated by a downward arrow).
- Interrupt or System Call:** Another event triggers the OS to perform another context switch.
- Save State:** The OS saves the state of P_1 into its PCB₁ (represented by a box labeled "save state into PCB₁").
- Reload State:** The OS reloads the state of P_0 from its PCB₀ (represented by a box labeled "reload state from PCB₀").
- Idle Period:** The OS is in an "idle" state (indicated by a bracket labeled "idle") while the state is being saved and reloaded.
- Execution Resumes:** Process P_0 resumes "executing" (indicated by a downward arrow).

Threads


- “Original” Process: address space and (single) flow of execution
 - Thread
 - we must separate address space (*process* or *task*) and flow of execution (*thread* or *lightweight process*, *LWP*)
- Motivation:
 - Context switch between cooperating processes is HUGE (reestablishing address space); context switch between cooperating threads is cheap
 - **fork(...)** of cooperating process is expensive; spawn of thread is cheap
 - programming is easier(?)



traditional UNIX



embedded systems



Windows, Solaris (POSIX)

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Threads and Address Space

The diagram illustrates the relationship between threads and address space. A large vertical rectangle represents the 'gigabyte virtual address space'. At the top, a blue grid represents 'files, I/O'. Below it, three horizontal blue grids represent 'stacks'. Three threads are shown on the right, each with a box labeled 'PC Registers'. Arrows point from each 'PC Registers' box to a specific location within the address space: the top thread points to the 'files, I/O' area, the middle thread points to the main address space, and the bottom thread points to one of the 'stacks'. The threads are labeled TCB1, TCB2, and TCB3.

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Kernel Threads

- An improvement over only processes
- Creation/Switching still requires trapping to the kernel (system call)
- Thread data structure resides within the kernel:
 - *Thread Control Block (TCB)* (execution state and scheduling info), so more complexity for the kernel
- Only one scheduling policy per system
- OS (still) does not trust the user, so there must be a lot of checking on kernel calls

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User-level Threads

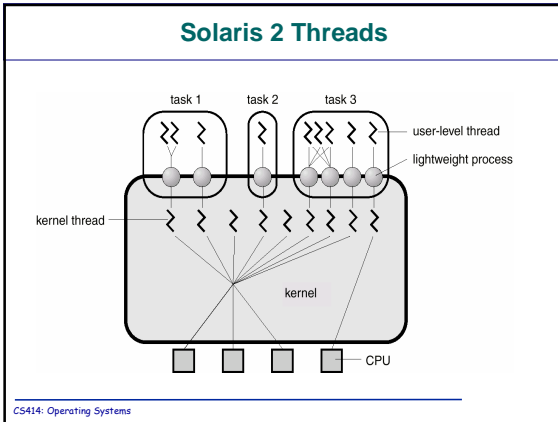
- **Faster than kernel-level threads**
 - In what sense?
- **Managed by run-time system in user-space (no kernel calls)**
- **Creation, switching, and synchronizing between thread calls can be done without kernel involvement**
- **Process-specific scheduling policies are possible**
- **Problem: whole process blocks when one thread blocks (there are ways around this, but they're complex)**
- **OS can make poor scheduling choices, because OS has no notion of "amount of work" each process must do**

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“Hybrid”: Solaris 2

- **Solaris 2 is a version of UNIX with support for threads at the kernel and user levels, symmetric multiprocessing, and real-time scheduling.**
- **LWP – intermediate level between user-level threads and kernel-level threads.**
- **Resource needs of thread types:**
 - **Kernel thread:** small data structure and a stack; thread switching does not require changing memory access information – relatively fast.
 - **LWP:** PCB with register data, accounting and memory information;; switching between LWPs is relatively slow.
 - **User-level thread:** only need stack and program counter; no kernel involvement means fast switching. Kernel only sees the LWPs that support user-level threads.

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Creation of a Thread

1. The thread count in the process object is incremented.
2. An executive thread block (ETHREAD) is created and initialized.
3. A thread ID is generated for the new thread.
4. The TEB is set up in the user-mode address space of the process.
5. The user-mode thread start address is stored in the ETHREAD.

Creation of a Thread

6. `KelInitThread` is called to set up the `KTHREAD` block.
 - The thread's initial and current base priorities are set to the process's base priority, and its affinity and quantum are set to that of the process.
 - `KelInitThread` allocates a kernel stack for the thread and initializes the machine-dependent hardware context for the thread, including the context, trap, and exception frames.
 - The thread's context is set up so that the thread will start in kernel mode in `KThreadStartup`.
 - Finally, `KelInitThread` sets the thread's state to `Initialized` and returns to `PspCreateThread`.
7. Any registered systemwide thread creation notification routines are called.
8. The thread's access token is set to point to the process access token.
 - an access check is made to determine whether the caller has the right to create the thread.
9. Finally, the thread is readied for execution.

Linux Pthreads: Kernel or User-Level – How to tell?

Run a pthread program, try to infer behavior

- PRO: No need to inspect kernel code
- CON: What behavior are we looking for? (what's the hypothesis?) – what's the test case?

Google for the answer

- PRO: Where exactly to find the answer?
 - <http://www.tldp.org/FAQ/Threads-FAQ/OSsCompared.html>
- CON: Could be wrong; might learn more by "doing it yourself"

Linker line has "-lpthread", so it must be user-level

- Not necessarily – this could be just for the `pthread` api, not the "entire pthreads implementation"

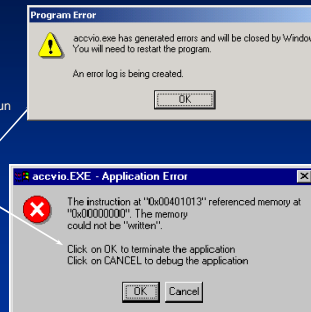
Evidence: hmmm....

- "`grep -i thread um/linux-2.4.26/kernel/* | wc -l`" returns 98
- "`grep -i thread um/linux-2.4.26/arch/i386/kernel/entry.S`" returns essentially nothing...

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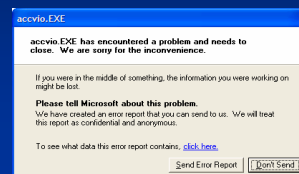
Process Crashes (Windows 2000)

- Registry defines behavior for unhandled exceptions
 - `HKLM\Software\Microsoft\Windows NT\CurrentVersion\AeDebug`
 - Debugger=filespec of debugger to run on app crash
 - Auto 1=run debugger immediately
 - Auto 0=ask user first
- Default on retail system is
 - Auto=1; Debugger=DRWTSN32.EXE
- Default with VC++ is
 - Auto=0; Debugger=MSDEV.EXE



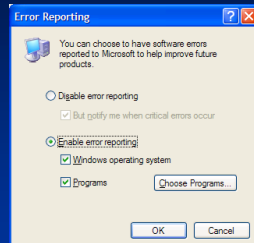
Process Crashes (Windows XP & Windows Server 2003)

- On XP & Server 2003, when an unhandled exception occurs:
 - System first runs `DWWIN.EXE`
 - `DWWIN` creates a process microdump and XML file and offers the option to send the error report
 - Then runs debugger (default is `Dwtsn32.exe`)

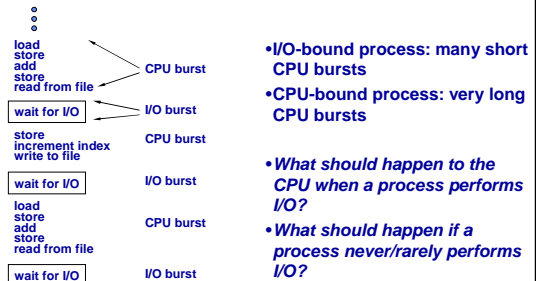


Windows Error Reporting

- Configurable with System Properties->Advanced->Error Reporting
 - HKLM\SOFTWARE\Microsoft\PCHealth\ErrorReporting
- Configurable with group policies
 - HKLM\SOFTWARE\Policies\Microsoft\PCHealth



Motivation for Scheduling: CPU and I/O Bursts



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Scheduling

- Multiprogramming:**
 - running more than one process at a time enables the OS to increase system utilization and throughput by overlapping I/O and CPU activities
- [Policy vs. Mechanism]**
 - what to do vs. how to do it
 - separation is crucial! WHY?
- [Process Execution State] remember from a few classes ago**
 - new, ready, running, waiting, terminated
- [Long-Term Scheduling]**
 - How does the OS determine the degree of multiprogramming (the number of jobs executing at once in primary memory)?
 - Invoked very infrequently (seconds, minutes → may be slow)
- [Short-Term Scheduling]**
 - How does the OS select a process from the ready Q to execute?
 - Invoked very frequently (milliseconds → must be fast)

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Context Switches: Voluntary vs. Involuntary

- Voluntary**
 - context switcher is invoked by the process that intends to relinquish the CPU (**nonpreemptive** scheduling); "yield" is for cooperative model
 - I/O requests and termination can also invoke context switcher
- Involuntary**
 - Interrupt handler executes context switcher (preemptive scheduling)
 - Interval timer is used

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Scheduling Criteria

- user-oriented, performance-related**
 - [Response Time] (can be referred to as "wait time") time from submission of job to start of execution of job
 - [Turnaround Time] time from submission of job to completion of job
 - [Deadlines] time at which computation must complete
- user-oriented, other**
 - [Predictability] job should run about the same amount of time regardless of load
- system-oriented, performance-related**
 - [Throughput] jobs completed per unit time
 - [Processor Utilization] percentage of time that processor is busy
- system-oriented, other**
 - [Fairness] jobs should be treated the same
 - [Balancing Resources] keep all resources busy

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Algorithm Evaluation

- [deterministic modeling]**
 - take a particular predefined workload and evaluation algorithm(s) (like gantt charts); gives exact numbers -- easy to compare; limited applicability (too specific); (this is what we'll focus on)
- [queuing models]**
 - use *distribution* of characteristics of arrivals (arrival times and execution times); math can sometimes be difficult; too many independent assumptions
- [simulation]**
 - programming a model of the computer system; random-number generators; can be expensive to develop
- [implementation]**
 - actual implement it and evaluate it in "real operation"; difficulties: cost, what if environment changes?

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Nonpreemptive Scheduling Policies

Important: Assume jobs are independent unless otherwise stated

- **First-in First-Out (FIFO):** execute jobs to completion in the order of their arrival
- **Example:** assume context switch time of 0 seconds; if 2 jobs arrive at the same time, then job with "lower number" arrived first

Job	Arrival	Duration	Response	Turnaround
1	0	50		
2	0	40		
3	10	30		
4	10	20		
5	20	10		

Advantage: simple

Disadvantages: short jobs may wait behind long jobs; may lead to poor overlap of I/O and CPU; not appropriate for timesharing situations

What does the Gantt chart look like?

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